AVC Plan

Robot name: Apollo 100

Team members and roles (Note. we all plan to help on all things so roles are only a rough guideline):

-Thomas Edwards - Lead/Manager

-Julian Schurhammer - Software

-Nicky McCleery - Hardware

-Harry Just - Hardware

-Adam Jiang – Software

Our full plan and weekly up to date progress can be found on Git hub

Link to Team GitHub: <https://github.com/harryJst/AVCTeam3>

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| Week | Dates | Team Objectives | Due | Conflicts | Task outline |
| 1 | 18April | Organise everything | 22 April AVC PLAN | Phys 122 test | * + Thomas- Organise things and set up Git Page   + Julian - Write test code for moving robot   + Nicky & Harry - Build first chassis   + Adam - Gather info on networking gate   + Everyone- Facebook and group chat |
| Holiday | 25April | Finish off Week 1 tasks if not done |  |  |  |
| 2 | 2May | Have the robot moving through networking gate |  |  | * + Thomas- Review and write up progress & help   + Julian - Write test code for following white line   + Nicky & Harry - Work on upgrading chassis   + Adam - Write code for networking gate |
| 3 | 9May | Have the robot chassis design finalised and have the robot following white line  Quadrant 2 complete |  | Comp 102 test | * + Thomas- Review and write up progress & help   + Julian - Write test code for turning with white line   + Nicky - Work on chassis or help with code   + Harry - Work on chassis or help with code   + Adam - Help with code for turning and overcoming intersections |
| 4 | 16May | Quadrant 3 complete | Progress Report | ENGR 121 test | * + Update results, work on quadrant 3 |
| 5 | 23May | Quadrant 4 complete |  |  | * + Update results, work on quadrant 4 |
| 6 | 30May | Everything complete | ROBOT due | ENGR 101 test | * + Update results, work on anything if behind |
| 7 | 6June |  |  |  |  |
| 8 | 13June |  | Final Report due |  |  |